

Proving Expected Sensitivity of Probabilistic Programs

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Program Sensitivity

Similar inputs \rightarrow similar outputs

- ▶ Given: distances d_{in} on inputs, d_{out} on outputs
- ▶ Want: for all inputs in_1, in_2 ,

$$d_{out}(P(in_1), P(in_2)) \leq d_{in}(in_1, in_2)$$

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If P is sensitive and Q is sensitive,
then $Q \circ P$ is sensitive

Probabilistic Program Sensitivity?

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What distance d_{out} should we take?

Our contributions

- Coupling-based definition of probabilistic sensitivity
- Relational program logic $\mathbb{E}PRHL$
- Formalized examples: stability and convergence

What is a good definition
of probabilistic sensitivity?

One possible definition: output distributions close

For two distributions μ_1, μ_2 over a set A :

$$d_{out}(\mu_1, \mu_2) \triangleq k \cdot \max_{E \subseteq A} |\mu_1(E) - \mu_2(E)|$$

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k -Uniform sensitivity

- ▶ Larger $k \rightarrow$ closer output distributions
- ▶ Strong guarantee: probabilities close for **all** sets of outputs

Application: probabilistic convergence/mixing

Probabilistic program forgets initial state

- ▶ Given: probabilistic loop, two different input states
- ▶ Want: state distributions converge to same distribution

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Consequence of k -uniform sensitivity

- ▶ As number of iterations T increases, prove k -uniform sensitivity for larger and larger $k(T)$
- ▶ Relation between k and T describes speed of convergence

Another possible definition: average outputs close

For two distributions μ_1, μ_2 over real numbers:

$$d_{out}(\mu_1, \mu_2) \triangleq k \cdot |\mathbb{E}[\mu_1] - \mathbb{E}[\mu_2]|$$

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k -Mean sensitivity

- ▶ Larger $k \rightarrow$ closer averages
- ▶ Weaker guarantee than uniform sensitivity

Application: algorithmic stability

Machine learning algorithm A

- ▶ Input: set S of training examples
- ▶ Output: list of numeric parameters (randomized)

Danger: overfitting

- ▶ Output parameters depend too much on training set S
- ▶ Low error on training set, high error on new examples

Application: algorithmic stability

One way to prevent overfitting

- ▶ L maps S to **average error** of randomized learning algorithm A
- ▶ If $|L(S) - L(S')|$ is small for all training sets S, S' differing in a single example, then A does not overfit too much

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L should be **mean sensitive**

Wanted: a general definition that is ...

- Expressive
- Easy to reason about

Ingredient #1: Probabilistic coupling

A **coupling** models two distributions with one distribution

Given two distributions $\mu_1, \mu_2 \in \text{Distr}(A)$, a joint distribution $\mu \in \text{Distr}(A \times A)$ is a **coupling** if

$$\pi_1(\mu) = \mu_1 \quad \text{and} \quad \pi_2(\mu) = \mu_2$$

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Typical pattern

Prove property about two (output) distributions by **constructing** a coupling with certain properties

Ingredient #2: Lift distance on outputs

Given:

- ▶ Two distributions $\mu_1, \mu_2 \in \text{Distr}(A)$
- ▶ Ground distance $d : A \times A \rightarrow \mathbb{R}^+$

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Define distance on distributions:

$$d^\#(\mu_1, \mu_2) \triangleq \min_{\mu \in C(\mu_1, \mu_2)} \mathbb{E}_\mu[d]$$

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Typical pattern

Bound distance $d^\#$ between two (output) distributions by **constructing** a coupling with small average distance d

set of all couplings

Putting it together: Expected sensitivity

Given:

- ▶ A function $f : A \rightarrow \text{Distr}(B)$ (think: probabilistic program)
- ▶ Distances d_{in} and d_{out} on A and B

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- ▶ A function $f : A \rightarrow \text{Distr}(B)$ (think: probabilistic program)
- ▶ Distances d_{in} and d_{out} on A and B

We say f is (d_{in}, d_{out}) -expected sensitive if:

$$d_{out}^{\#}(f(a_1), f(a_2)) \leq d_{in}(a_1, a_2)$$

for all inputs $a_1, a_2 \in A$.

Benefits: Expressive

If $d_{out}(b_1, b_2) > k$ for all distinct b_1, b_2 :

(d_{in}, d_{out}) -expected sensitive $\implies k$ -uniform sensitive

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If $d_{out}(b_1, b_2) > k$ for all distinct b_1, b_2 :

(d_{in}, d_{out}) -expected sensitive $\implies k$ -uniform sensitive

If outputs are real-valued and $d_{out}(b_1, b_2) = k \cdot |b_1 - b_2|$:

(d_{in}, d_{out}) -expected sensitive $\implies k$ -mean sensitive

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Abstract away distributions

- ▶ Work in terms of distances on ground sets
- ▶ No need to work with complex distances over distributions

How to verify this property?
The program logic $\mathbb{E}PRHL$

A relational program logic $\mathbb{E}PRHL$

The pWhile imperative language

$c ::= x \leftarrow e \mid x \overset{\$}{\leftarrow} d \mid \text{if } e \text{ then } c \text{ else } c \mid \text{while } e \text{ do } c \mid \text{skip} \mid c; c$

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Judgments

$$\vdash \{P; d_{in}\} \quad c_1 \sim c_2 \quad \{Q; d_{out}\}$$

- ▶ Tagged program variables: $x\langle 1 \rangle, x\langle 2 \rangle$
- ▶ P and Q : boolean predicates over tagged variables
- ▶ d_{in} and d_{out} : real-valued expressions over tagged variables

\mathbb{E} PRHL judgments model expected sensitivity

A judgment

$$\vdash \{P; d_{in}\} \quad c_1 \sim c_2 \quad \{Q; d_{out}\}$$

is valid if:

for all input memories (m_1, m_2) satisfying pre-condition P , there **exists** a coupling of outputs $(\llbracket c_1 \rrbracket m_1, \llbracket c_2 \rrbracket m_2)$ with

- ▶ support satisfying post-condition Q
- ▶ $\mathbb{E}[d_{out}] \leq d_{in}(m_1, m_2)$

One proof rule: Sequential composition

$$\vdash \{P; d_A\} \quad c_1 \sim c_2 \quad \{Q; d_B\}$$

$$\vdash \{Q; d_B\} \quad c'_1 \sim c'_2 \quad \{R; d_C\}$$

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Expected sensitivity composes

Wrapping up

More in the paper

Theoretical results

- ▶ Full proof system (sampling, conditionals, loops, etc.)
- ▶ Transitivity principle (internalizes **path coupling**)

Implementation in EasyCrypt, formalizations of:

- ▶ Stability for the Stochastic Gradient Method
- ▶ Convergence for the RSM population dynamics
- ▶ Mixing for the Glauber dynamics

Looking forward

Possible directions

- ▶ Other useful consequences of expected sensitivity?
- ▶ Formal verification systems beyond program logics?
- ▶ How to automate this proof technique?

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Shameless plug: Looking for
students at **UWisconsin!**

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